

# Amplitude Modulation Demodulation using MATLAB SIMULINK model

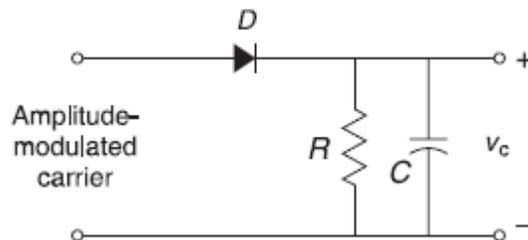
*The following gives implementation of Amplitude Modulation Demodulation (Double Side Band with Carrier or DSB-C) on MATLAB SIMULINK model. For the theoretical background of DSB-C please refer to Section 3.3 of the text book titled 'Principles of Communication Systems', Third Edition by Herbert Taub, Donald L Schilling and Goutam Saha. To get introductory ideas of MATLAB SIMULINK model development please refer to Chapter 10, MATLAB Experiments 42 and 43 of the above referenced book. We implement non-coherent DSB-C demodulator here which does not require a synchronized local oscillator for demodulation. The coherent detection, useful for DSB-C with modulation index greater than one or suppressed carrier is implemented later.*

The DSB-C modulator output follows eqn. (3.8) as given next.

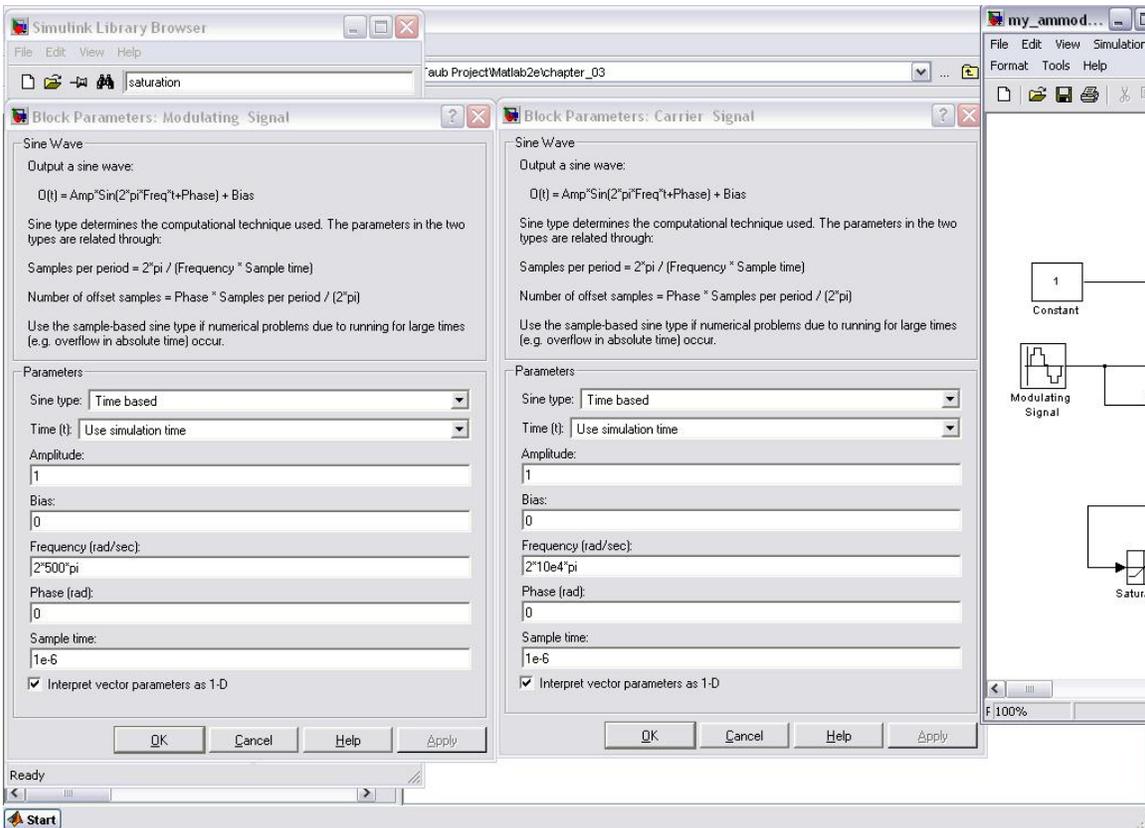
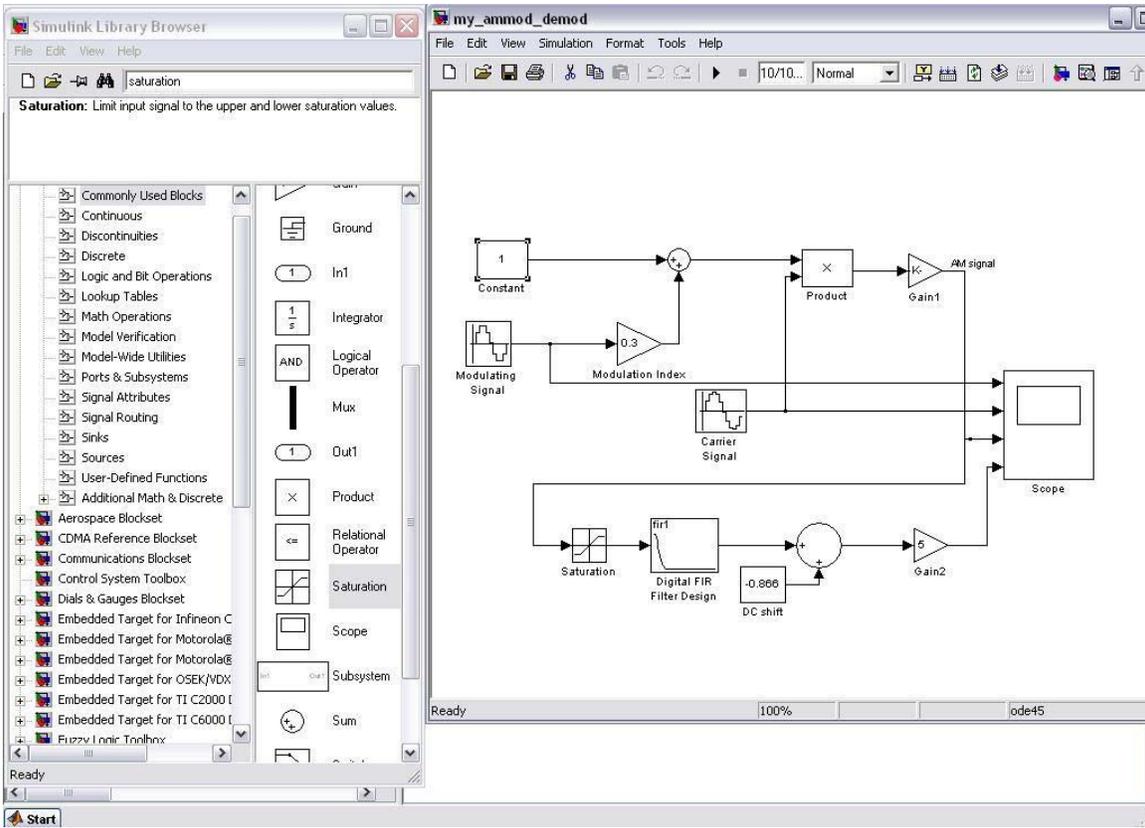
$$v(t) = A_c[1 + m(t)] \cos \omega_c t$$

The SIMULINK model considers a sinusoidal (500 Hz) message signal as shown in following figure. To consider a different type of modulating signal this block needs to be changed. At the end we show the performance of the system for a message signal which is a composite of two sinusoidal signals. The carrier frequency is much higher (10000 Hz) while modulating index is made to vary to show the performance for different modulating index.

The DSB-C demodulator is non-coherent type which is simple to design and consists of a diode and a Low Pass Filter (LPF) as shown below.



In SIMULINK the diode is implemented by a saturation block which is clipped in the lower side to 0 instead of default -1. LPF filter is implemented by a FIR1 block which is a 32 order Chebyshev Filter, however other filter type will also do. The time scope shows modulating signal, carrier signal, modulated signal, demodulated signal from top to bottom of the plot. In following four figures we show the SIMULINK model and how parameterization is done for each block for first simulation. Note that, modulation index used = 0.3.



**Block Parameters: Constant**

Constant

Output the constant specified by the 'Constant value' parameter. If 'Constant value' is a vector and 'Interpret vector parameters as 1-D' is on, treat the constant value as a 1-D array. Otherwise, output a matrix with the same dimensions as the constant value.

Main | Signal data types

Constant value:  
1

Interpret vector parameters as 1-D

Sample time:  
inf

OK Cancel Help Apply

**Block Parameters: Product**

Product

Multiply or divide inputs. Choose element-wise or matrix product and specify one of the following:  
a) \* or / for each input port (e.g. \*//)  
b) scalar specifies the number of input ports to be multiplied  
Scalar value of '1' for element-wise product causes all elements of a single input vector to be multiplied.  
If / is specified with matrix product, compute the inverse of the corresponding input.

Main | Signal data types

Number of inputs:  
2

Multiplication: Element-wise(\*)

Sample time (-1 for inherited):  
-1

OK Cancel Help Apply

**Block Parameters: Modulation Index**

Gain

Element-wise gain ( $y = K \cdot u$ ) or matrix gain ( $y = K \cdot u$  or  $y = u \cdot K$ ).

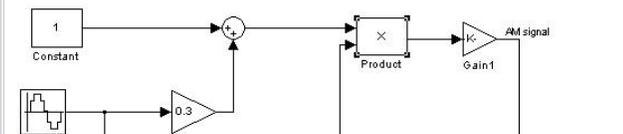
Main | Signal data types | Parameter data types

Gain:  
0.3

Multiplication: Element-wise(K.\*u)

Sample time (-1 for inherited):  
-1

OK Cancel Help Apply



**Block Parameters: Sum**

Sum

Add or subtract inputs. Specify one of the following:  
a) string containing + or - for each input port, | for spacer between ports (e.g. ++|+)  
b) scalar >= 1. A value > 1 sums all inputs; 1 sums elements of a single input vector

Main | Signal data types

Icon shape: round

List of signs:  
|++

Sample time (-1 for inherited):  
-1

OK Cancel Help Apply

**Block Parameters: Gain1**

Gain

Element-wise gain ( $y = K \cdot u$ ) or matrix gain ( $y = K \cdot u$  or  $y = u \cdot K$ ).

Main | Signal data types | Parameter data types

Gain:  
 $2 \cdot \sqrt{2}$

Multiplication: Element-wise(K.\*u)

Sample time (-1 for inherited):  
-1

OK Cancel Help Apply

**Block Parameters: Saturation**

Saturation

Limit input signal to the upper and lower saturation values.

Parameters

Upper limit:  
10

Lower limit:  
0

Treat as gain when linearizing

Enable zero crossing detection

Sample time (-1 for inherited):  
-1

OK Cancel Help Apply

**Block Parameters: DC shift**

Constant

Output the constant specified by the 'Constant value' parameter. If 'Constant value' is a vector and 'Interpret vector parameters as 1-D' is on, treat the constant value as a 1-D array. Otherwise, output a matrix with the same dimensions as the constant value.

Main | Signal data types

Constant value:  
0.866

Interpret vector parameters as 1-D

Sample time:  
inf

OK Cancel Help Apply

**Block Parameters: Digital FIR Filter Design**

Digital FIR Filter Design (mask) (link)

Implements various window-based FIR filter designs using the Signal Processing Toolbox's 'fir1' and 'fir2' filter design commands. The gain at each 'cutoff frequency' is the average of the gains in the adjacent bands (usually 0.5).

Parameters

Filter type: Lowpass

Filter order:  
32

Cutoff frequency (0 to 1):  
0.05

Window type: Chebyshev

Stopband attenuation in dB:  
80

Beta:  
5

OK Cancel Help Apply

**Block Parameters: Sum1**

Sum

Add or subtract inputs. Specify one of the following:  
a) string containing + or - for each input port, | for spacer between ports (e.g. ++|+)  
b) scalar >= 1. A value > 1 sums all inputs; 1 sums elements of a single input vector

Main | Signal data types

Icon shape: round

List of signs:  
|++

Sample time (-1 for inherited):  
-1

OK Cancel Help Apply

**Block Parameters: Gain2**

Gain

Element-wise gain ( $y = K \cdot u$ ) or matrix gain ( $y = K \cdot u$  or  $y = u \cdot K$ ).

Main | Signal data types | Parameter data types

Gain:  
5

Multiplication: Element-wise(K.\*u)

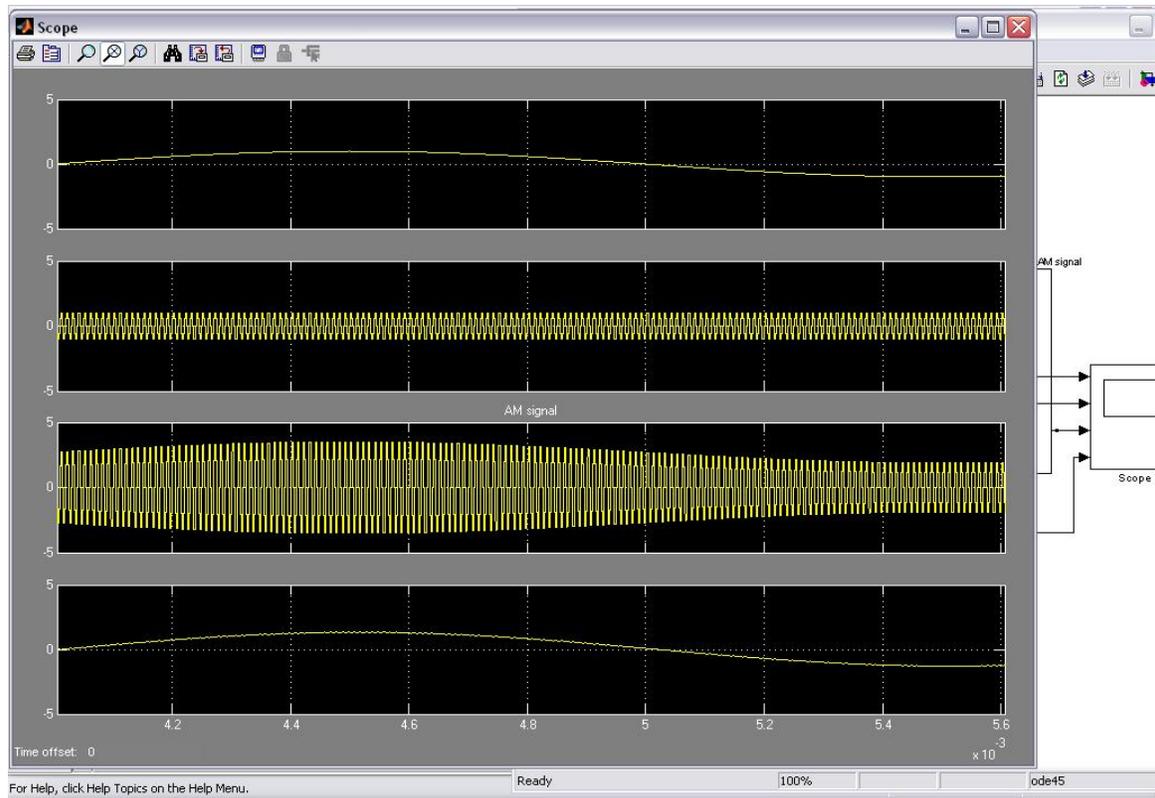
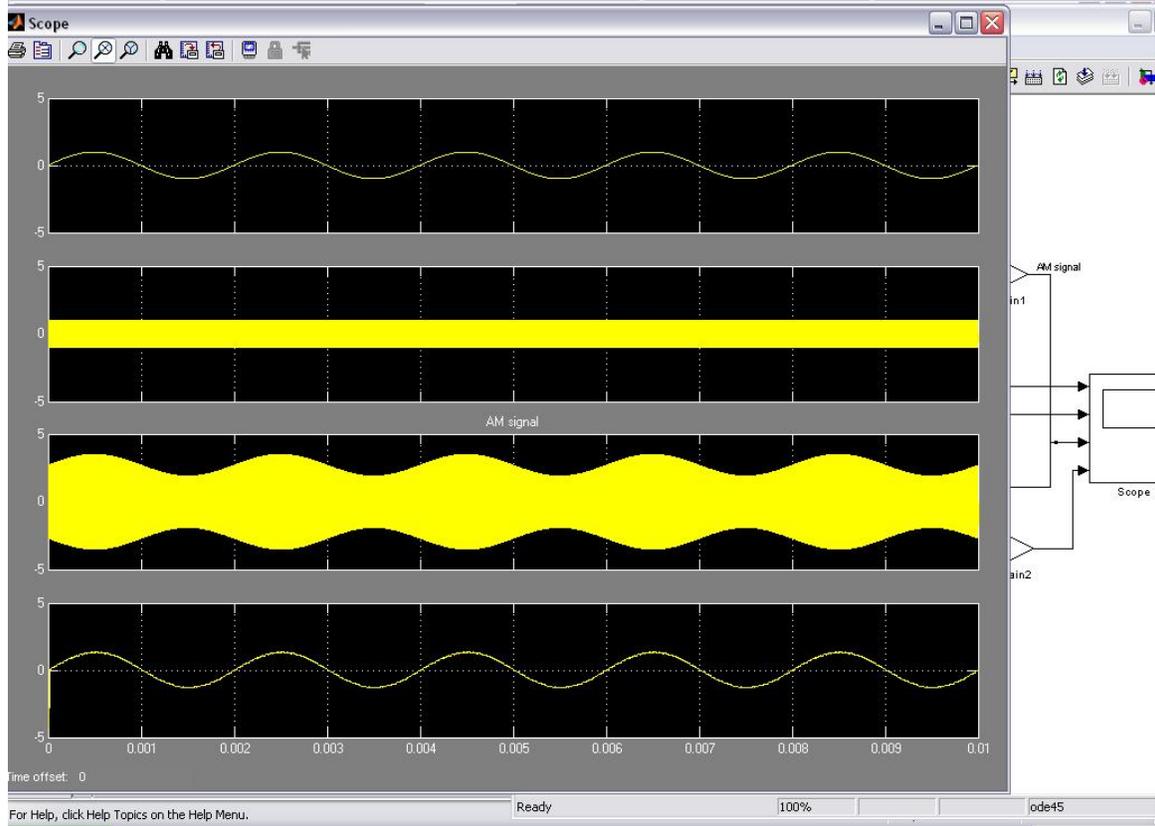
Sample time (-1 for inherited):  
-1

OK Cancel Help Apply

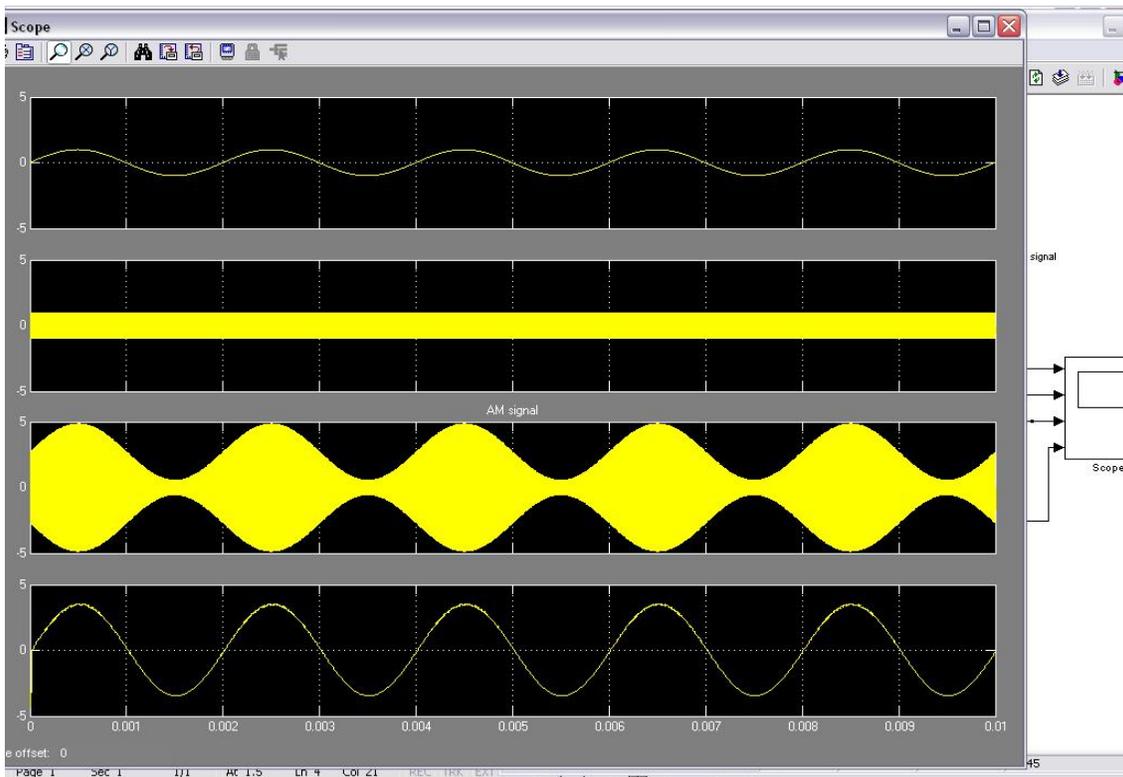
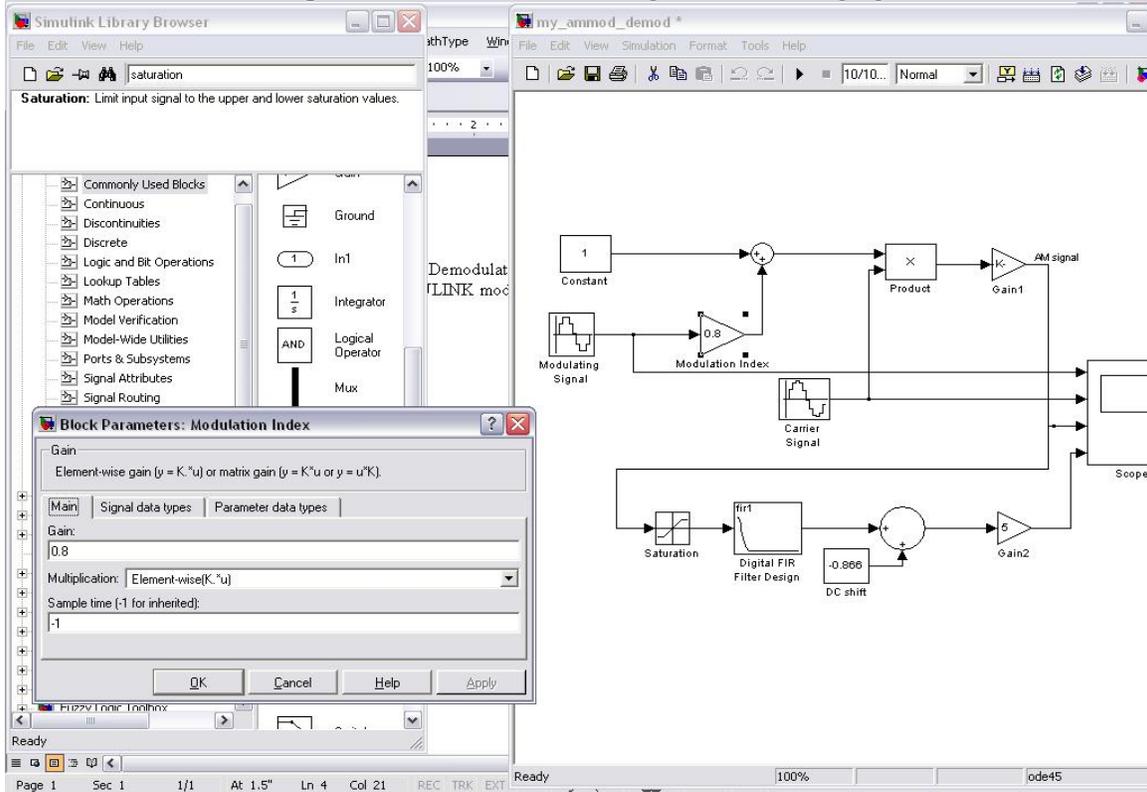
For Help, click Help Topics on the Help Menu.

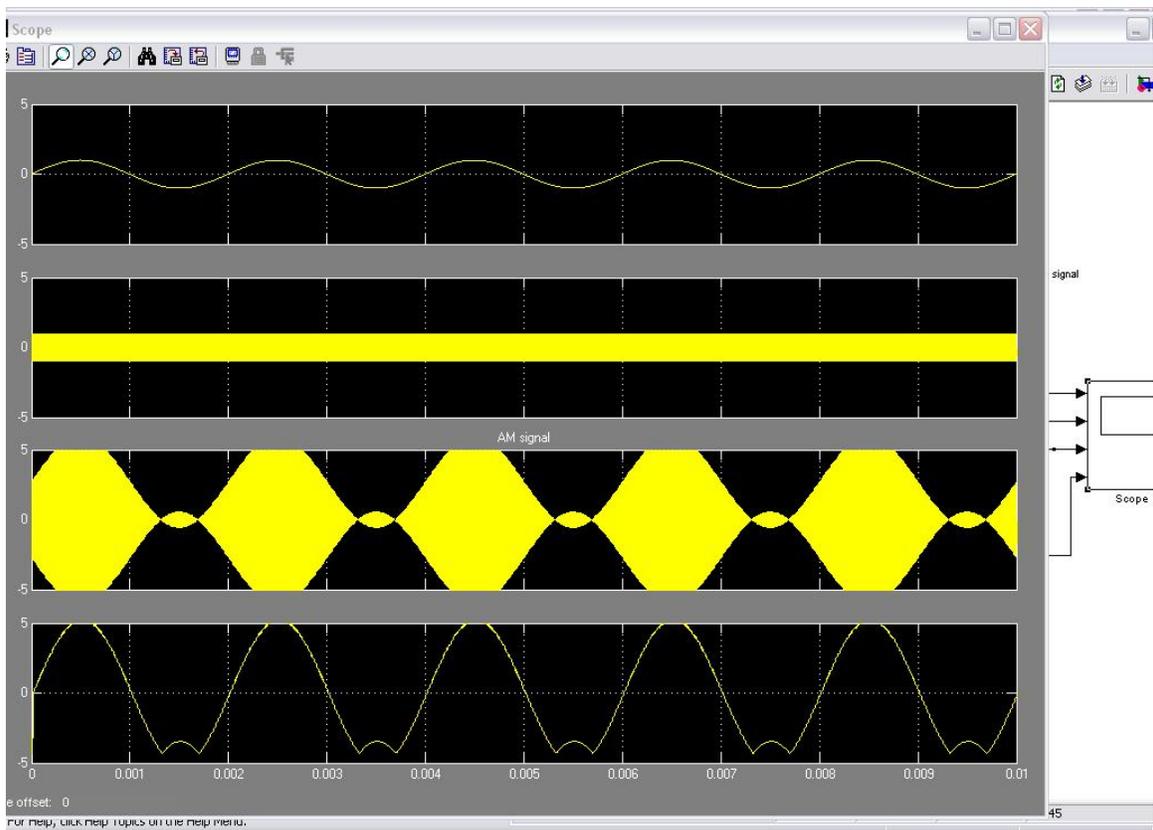
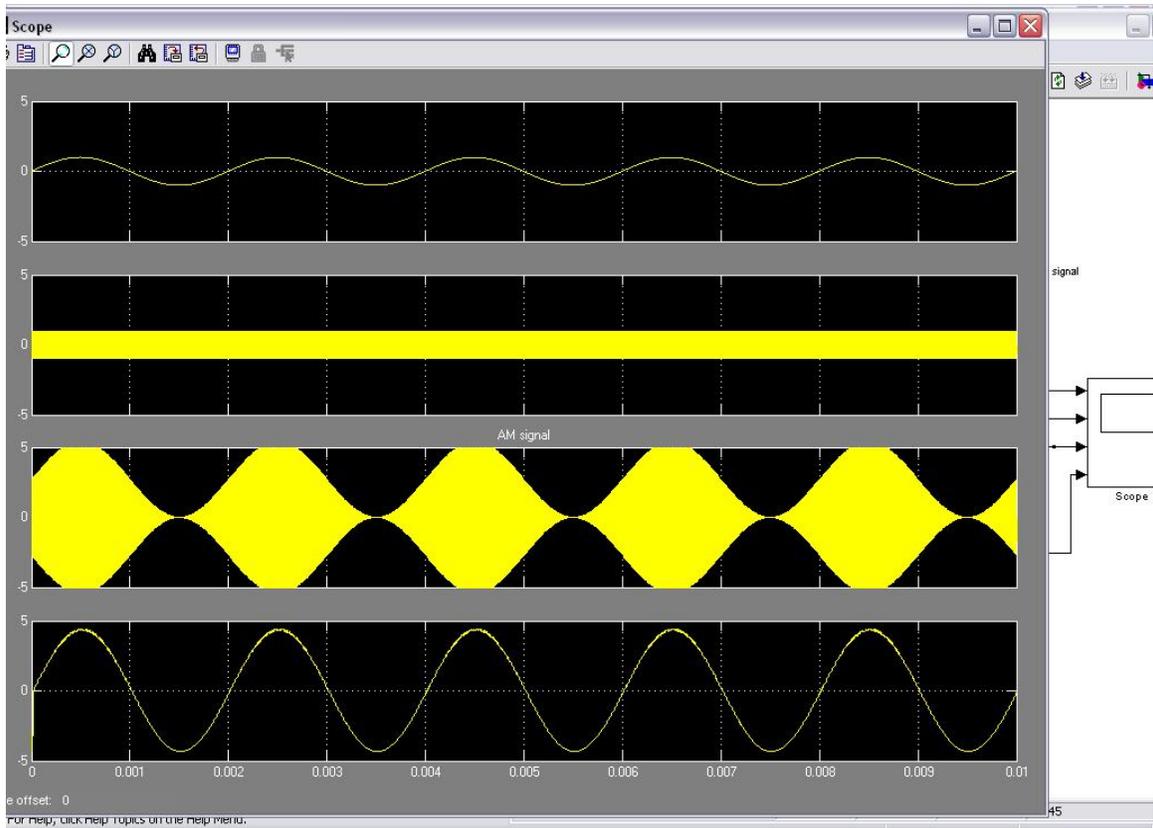
Ready

Next are the plots of simulation for 10 ms on time scope in default and expanded X-axis mode.



Next are the plots of simulation for 10 ms on time scope for modulation index 0.8. This we follow for modulation indices 1.0, 1.2. Note that for 1.2 demodulated signal is distorted. Coherent detector can extract the signal in this case which we implement in next project.





Next is the model for a composite modulating signal and its simulation. Note the frequency and amplitudes of two sinusoidal signals that makes the composite. Note that amplitude of composite signal does not exceed 1. The modulation index is kept at 0.8.

