## Computer Problems

4.C1 A slender $\operatorname{rod} A B$ of weight $W$ is attached to blocks at $A$ and $B$ which can move freely in the guides shown. The constant of the spring is $k$ and the spring is unstretched when the rod is horizontal. Neglecting the weight of the blocks, derive an equation in terms of $(\theta, W, l$, and $k$ which must be satisfied when the rod is in equilibrium. Knowing that $W=10 \mathrm{lb}$ and $l=40 \mathrm{in}$., (a) calculate and plot the value of the spring constant $k$ as a function of the angle $\theta$ for $15^{\circ} \leq \theta \leq 40^{\circ}$, (b) determine the two values of the angle $\theta$ corresponding to equilibrium when $k=0.7 \mathrm{lb} / \mathrm{in}$.


Fig. P4.C1
4.C2 The position of the L-shaped rod shown is controlled by a cable attached at point $B$. Knowing that the rod supports a load of magnitude $P=$ 200 N , use computational software to calculate and plot the tension $T$ in the cable as a function of $\theta$ for values of $\theta$ from from 0 to $120^{\circ}$. Determine the maximum tension $T_{\max }$ and the corresponding value of $\theta$.
4.C3 The position of the $20-\mathrm{lb} \operatorname{rod} A B$ is controlled by the block shown, which is slowly moved to the left by the force $\mathbf{P}$. Neglecting the effect of friction, use computational software to calculate and plot the magnitude $P$ of the force as a function of $x$ for values of $x$ decreasing from 30 in. to 0 . Determine the maximum value of $P$ and the corresponding value of $x$.


Fig. P4.C2


Fig. P4.C3


Fig. P4.C4


Fig. P4.C5
*4.C4 Member $A B C$ is supported by a pin and bracket at $C$ and by an inextensible cable of length 3.5 m that is attached at $A$ and $B$ and passes over a frictionless pulley at $D$. Neglecting the mass of $A B C$ and the radius of the pulley, ( $a$ ) plot the tension in the cable as a function of $a$ for $0 \leq a \leq 2.4 \mathrm{~m}$, (b) determine the largest value of $a$ for which equilibrium can be maintained.
4.C5 and 4.C6 The constant of spring $A B$ is $k$, and the spring is unstretched when $\theta=0$. Knowing that $R=200 \mathrm{~mm}, a=400 \mathrm{~mm}$, and $k=$ $1 \mathrm{kN} / \mathrm{m}$, use computational software to calculate and plot the mass $m$ corresponding to equilibrium as a function of $\theta$ for values of $\theta$ from 0 to $90^{\circ}$. Determine the value of $\theta$ corresponding to equilibrium when $m=2 \mathrm{~kg}$.


Fig. P4.C6
4.C7 An $8 \times 10-\mathrm{in}$. panel of weight $W=40 \mathrm{lb}$ is supported by hinges along edge $A B$. Cable $C D E$ is attached to the panel at point $C$, passes over a small pulley at $D$, and supports a cylinder of weight $W$. Neglecting the effect of friction, use computational software to calculate and plot the weight of the cylinder corresponding to equilibrium as a function of $\theta$ for values of $\theta$ from 0 to $90^{\circ}$. Determine the value of $\theta$ corresponding to equilibrium when $W=20 \mathrm{lb}$.


Fig. P4.C7
4.C8 A uniform circular plate of radius 300 mm and mass 26 kg is supported by three vertical wires that are equally spaced around its edge. A small $3-\mathrm{kg}$ block $E$ is placed on the plate at $D$ and is then slowly moved along diameter $C D$ until it reaches $C$. (a) Plot the tension in wires $A$ and $C$ as functions of $a$, where $a$ is the distance of the block from $D$. (b) Determine the value of $a$ for which the tension in wires $A$ and $C$ is minimum.


Fig. P4.C8
4.C9 The derrick shown supports a 4000-lb crate. It is held by a ball-and-socket joint at point $A$ and by two cables attached at points $D$ and $E$. Knowing that the derrick lies in a vertical plane forming an angle $\phi$ with the $x y$ plane, use computational software to calculate and plot the tension in each cable as a function of $\phi$ for values of $\phi$ from 0 to $40^{\circ}$. Determine the value of $\phi$ for which the tension in cable $B E$ is maximum.
4.C10 The $140-\mathrm{lb}$ uniform steel plate $A B C D$ is welded to shaft $E F$ and is maintained in the position shown by the couple $\mathbf{M}$. Knowing that collars prevent the shaft from sliding in the bearings and that the shaft lies in the $y z$ plane, plot the magnitude $M$ of the couple as a function of $\theta$ for $0 \leq \theta \leq 90^{\circ}$.


Fig. P4.C9


Fig. P4.C10

