# MECHANICAL ENGINEERING DESIGN TUTORIAL 4-20: HERTZ CONTACT STRESSES

## CHARACTERISTICS OF CONTACT STRESSES

- 1. Represent *compressive* stresses developed from surface pressures between two curved bodies pressed together;
- 2. Possess an area of contact. The initial point contact (spheres) or line contact (cylinders) become area contacts, as a result of the force pressing the bodies against each other;
- 3. Constitute the principal stresses of a triaxial (three dimensional) state of stress;
- 4. Cause the development of a critical section below the surface of the body;
- 5. Failure typically results in flaking or pitting on the bodies' surfaces.

# **TWO DESIGN CASES**

Two design cases will be considered,

- 1. Sphere Sphere Contact (Point Contact  $\Rightarrow$  Circular Contact Area)
- 2. Cylinder Cylinder Contact (Line Contact  $\Rightarrow$  Rectangular Contact Area)

## SPHERE – SPHERE CONTACT



(a) Two spheres held in contact by force *F*.

(b) Contact stress has an elliptical distribution across contact over zone of diameter 2a.



<sup>†</sup> *Text.* refers to *Mechanical Engineering Design*, 7<sup>th</sup> edition text by Joseph Edward Shigley, Charles R. Mischke, and Richard G. Budynas; equations and figures with the prefix *T* refer to the present tutorial.

Consider two solid elastic spheres held in contact by a force F such that their point of contact expands into a circular area of radius a, given as:

$$a = K_a \sqrt[3]{F}$$
(Modified Text Eq. 4-72)  
where  $K_a = \left[\frac{3}{8} \frac{(1-v_1^2)/E_1 + (1-v_2^2)/E_2}{(1/d_1) + (1/d_2)}\right]^{1/3}$   
 $F = \text{ applied force}$   
 $v_1, v_2 = \text{ Poisson's ratios for spheres 1 and 2}$   
 $E_1, E_2 = \text{ elastic modulii for spheres 1 and 2}$   
 $d_1, d_2 = \text{ diameters of spheres 1 and 2}$ 

This general expression for the contact radius can be applied to two additional common cases:

- 1. Sphere in contact with a plane  $(d_2 = \infty)$ ;
- 2. Sphere in contact with an internal spherical surface or 'cup'  $(d_2 = -d)$ .

Returning to the sphere-sphere case, the maximum contact pressure,  $p_{max}$ , occurs at the center point of the contact area.

$$p_{\max} = \frac{3F}{2\pi a^2}$$
(Text Eq. 4-73)

#### State of Stress

- The state of stress is computed based on the following mechanics:
  - 1. Two planes of symmetry in loading and geometry dictates that  $\sigma_x = \sigma_y$ ;
  - 2. The dominant stress occurs on the axis of loading:  $\sigma_{\text{max}} = \sigma_z$ ;
  - 3. The principal stresses are  $\sigma_1 = \sigma_2 = \sigma_x = \sigma_y$  and  $\sigma_3 = \sigma_z$  given  $\sigma_1, \sigma_2 \ge \sigma_3$ ;
  - 4. Compressive loading leads to  $\sigma_x, \sigma_y$ , and  $\sigma_z$  being compressive stresses.
- Calculation of Principal Stresses

$$\sigma_{x} = -p_{\max}\left[\left[1 - |\zeta_{a}| \tan^{-1}\left(\frac{1}{|\zeta_{a}|}\right)\right](1 + \nu) - \frac{1}{2(1 + \zeta_{a}^{2})}\right] \qquad (\text{Modified Text Eq. 4-74})$$
$$= \sigma_{y} = \sigma_{1} = \sigma_{2}$$

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$$\sigma_3 = \sigma_z = \frac{-p_{\text{max}}}{1 + \zeta_a^2}$$
(Modified Text Eq. 4-75)

where  $\zeta_a = z/a$  = nondimensional depth below the surface v = Poisson's ratio for the sphere examined (1 or 2)

• Mohr's Circle

Plotting the principal stresses on a Mohr's circle plot results in: one circle, defined by  $\sigma_1 = \sigma_2$ , shrinking to a point; and two circles, defined by  $\sigma_1$ ,  $\sigma_3$  and  $\sigma_2$ ,  $\sigma_3$ , plotted on top of each other. The maximum shear stress,  $\tau_{max}$ , for the plot is calculated as:

$$\tau_{\max} = \frac{\sigma_1 - \sigma_3}{2} = \frac{\sigma_x - \sigma_z}{2} = \frac{\sigma_y - \sigma_z}{2}$$
(Modified Text Eq. 4-76)

If the maximum shear stress,  $\tau_{max}$ , and principal stresses,  $\sigma_1$ ,  $\sigma_2$ , and  $\sigma_3$ , are plotted as a function of maximum pressure,  $p_{max}$ , below the surface contact point, the plot of Fig. 4-43 is generated. This plot, based on a Poisson's ratio of v = 0.3, reveals that a critical section exists on the load axis, approximately 0.48*a* below the sphere surface. Many authorities theorize that this maximum shear stress is responsible for the surface fatigue failure of such contacting elements; a crack, originating at the point of maximum shear, progresses to the surface where lubricant pressure wedges a chip loose and thus creates surface pitting.



**TEXT FIGURE 4-43:** Magnitude of the stress components below the surface as a function of maximum pressure of contacting spheres.

# CYLINDER-CYLINDER CONTACT

Consider two solid elastic cylinders held in contact by forces F uniformly distributed along the cylinder length *l*.



TEXT FIGURE 4-44 Two Cylinders in Contact

The resulting pressure causes the line of contact to become a rectangular contact zone of halfwidth *b* given as:

(Modified Text Eq. 4-77)

$$b = K_b \sqrt{F}$$
  
where  $K_b = \left[\frac{2}{\pi l} \frac{(1 - v_1^2) / E_1 + (1 - v_2^2) / E_2}{(1/d_1) + (1/d_2)}\right]^{1/2}$   
 $F = \text{applied force}$   
 $v_1, v_2 = \text{Poisson's ratios for cylinders 1 and 2}$   
 $E_1, E_2 = \text{elastic modulii for cylinders 1 and 2}$   
 $d_1, d_2 = \text{diameters of spheres 1 and 2}$   
 $l = \text{length of cylinders 1 and 2} (l_1 = l_2 \text{ assumed})$ 

.

This expression for the contact half-width, *b*, is general and can be used for two additional cases which are frequently encountered:

- 1. Cylinder in contact with a plane, e.g. a rail  $(d_2 = \infty)$ ;
- 2. Cylinder in contact with an internal cylindrical surface, for example the race of a roller bearing  $(d_2 = -d)$ .

The maximum contact pressure between the cylinders acts along a longitudinal line at the center of the rectangular contact area, and is computed as:

$$p_{\max} = \frac{2F}{\pi bl}$$
(Text Eq. 4-78)

## State of Stress

- The state of stress is computed based on the following mechanics:
  - 1. One plane of symmetry in loading and geometry dictates that  $\sigma_x \neq \sigma_y$ ;
  - 2. The dominant stress occurs along the axis of loading:  $\sigma_{\text{max}} = \sigma_z$ ;
  - 3. The principal stresses are equal to  $\sigma_x, \sigma_y$ , and  $\sigma_z$  with  $\sigma_3 = \sigma_z$ ;
  - 4. Compressive loading leads to  $\sigma_x$ ,  $\sigma_y$ , and  $\sigma_z$  being compressive stresses.
- Calculation of Principal Stresses and Maximum Shear Stress

$$\sigma_{3} = \sigma_{z} = -p_{\max} \frac{1}{\sqrt{1 + \zeta_{b}^{2}}}$$
(Modified Text Eq. 4-81)  

$$\sigma_{1} = \begin{cases} \sigma_{x} & \text{for } 0 \le \zeta_{b} \le 0.436 \\ \sigma_{y} & \text{for } 0.436 \le \zeta_{b} \end{cases}$$

where,

$$\sigma_{x} = -2v p_{\max} \left[ \sqrt{1 + \zeta_{b}^{2}} - |\zeta_{b}| \right]$$
(Modified Text Eq. 4-79)
$$\sigma_{y} = -p_{\max} \left[ \left( \frac{1 + 2\zeta_{b}^{2}}{\sqrt{1 + \zeta_{b}^{2}}} \right) - 2|\zeta_{b}| \right]$$
(Modified Text Eq. 4-80)
$$\zeta_{b} = z/b$$

The maximum shear stress is thus given as:

$$\tau_{\max} = \begin{cases} \tau_{1/3} = (\sigma_z - \sigma_x)/2 & \text{for } 0 \le \zeta_b \le 0.436 \\ \tau_{1/3} = (\sigma_z - \sigma_y)/2 & \text{for } 0.436 \le \zeta_b \end{cases}$$

When these equations are plotted as a function of maximum contact pressure up to a distance 3b below the surface contact point, the plot of Fig. 4-45 is generated. Based on a Poisson's ratio of 0.3, this plot reveals that  $\tau_{\text{max}}$  attains a maxima for  $\zeta_b = z/b = 0.786$  and  $0.3p_{\text{max}}$ .



**TEXT FIGURE 4-45:** Magnitude of stress components below the surface as a function of maximum pressure for contacting cylinders.

#### **Example T4.20.1:**

**Problem Statement:** A 6-in-diameter cast-iron wheel, 2 in wide, rolls on a flat steel surface carrying a 800 lbf load.

#### Find:

- 1. The Hertzian stresses  $\sigma_x, \sigma_y, \sigma_z$  and  $\tau_{1/3}$  in the cast iron wheel at the critical section;
- 2. The comparative state of stress and maximum shear stress, arising during a revolution, at point *A* located 0.015 inch below the wheel rim surface.

#### **Solution Methodology:**

- 1. Compute the value of the contact half-width, *b*.
- 2. Compute the maximum pressure generated by the normal force of the wheel.
- 3. Use the results of steps (1) and (2) to calculate the contact stresses in the cast iron wheel for the critical section, z/b = 0.786.
- 4. Evaluate the principal stresses based upon the contact stress calculations.
- 5. Calculate the maximum shear stress.
- 6. Compare these results with those obtained by using Fig. 4-45.
- 7. During a single revolution of the wheel, point *A* will experience a cycle of stress values varying from zero (when point *A* lies well outside the contact zone) to a maximum state of stress (when *A* lies within the contact zone and on the line of action of the 800 lbf force.) We expect point *A* to "feel" the effects of a semi-elliptical contact pressure distribution as point *A* moves into and through the contact zone. Thus, we need to calculate the contact stresses for a depth of z = 0.015 inch, which we expect to lie within the contact zone.

#### Schematic:



#### Solution:

1. Compute contact half-width, b

Material Properties: 
$$E_1 = E_{\text{cast iron}} = 14.5 \times 10^6 \text{ psi}; v_1 = v_{\text{cast iron}} = 0.211$$
  
 $E_2 = E_{\text{steel}} = 30.0 \times 10^6 \text{ psi}; v_2 = v_{\text{steel}} = 0.292$ 

Dimensions:  $d_1$ 

$$d_1 = 6.0$$
 in;  $d_2 = \infty$ ;  $l = 2.0$  in

$$b = K_b \sqrt{F}$$
 (Modified Text Eq. 4-72)  

$$K_b = \left[\frac{2}{\pi l} \frac{(1 - v_1^2) / E_1 + (1 - v_2^2) / E_2}{(1 / d_1) + (1 / d_2)}\right]^{1/2}$$

$$= \left\{\frac{2}{\pi (2.0)} \frac{\left[1 - (0.211)^2\right] / (14.5 \times 10^6) + \left[1 - (0.292)^2\right] / (30.0 \times 10^6)}{(1 / 6.0) + (1 / \infty)}\right\}^{1/2}$$

$$= 4.291 \times 10^{-4} \text{ in} / \sqrt{\text{lbf}}$$

$$b = K_b \sqrt{F} = (4.291 \times 10^{-4} \text{ in} / \sqrt{\text{lbf}})(800 \text{ lbf})^{1/2} = 1.214 \times 10^{-2} \text{ in}$$

2. Maximum Pressure,  $p_{\text{max}}$ 

$$p_{\text{max}} = \frac{2F}{\pi bl} = \frac{2(800 \text{ lbf})}{\pi (1.214 \times 10^{-2} \text{ in})(2.0 \text{ in})} = 20\ 980 \text{ psi}$$

3. Hertz Contact Stresses in Cast Iron Wheel

At the critical section,  $\zeta_b = z/b = 0.786$ ,

$$\sigma_{x} = -2v_{1}p_{\max} \left[ \sqrt{1 + \zeta_{b}^{2}} - |\zeta_{b}| \right]$$

$$= -2(0.211)(20\,980\,\mathrm{psi}) \left[ \sqrt{1 + (0.786)^{2}} - 0.786 \right]$$

$$= -4302\,\mathrm{psi}$$

$$\sigma_{y} = -p_{\max} \left[ \left( \frac{1 + 2\zeta_{b}^{2}}{\sqrt{1 + \zeta_{b}^{2}}} \right) - 2|\zeta_{b}| \right]$$

$$= (-20\,980\,\mathrm{psi}) \left\{ \left[ \frac{1 + 2(0.786)^{2}}{\sqrt{1 + (0.786)^{2}}} \right] - 2(0.786) \right\}$$

$$= -3895\,\mathrm{psi}$$

$$\sigma_{z} = -p_{\max} \frac{1}{\sqrt{1 + \zeta_{b}^{2}}} = \frac{-20\,980\,\mathrm{psi}}{\sqrt{1 + (0.786)^{2}}}$$

$$= -16\,490\,\mathrm{psi}$$

Note that the small contact area involved in this type of problem gives rise to very high pressure, relative to the applied force, and thus exceptionally high stresses.

4. Since  $\sigma_x, \sigma_y$ , and  $\sigma_z$  are all principal stresses, we can conclude:

 $\sigma_1 = \sigma_y = -3895 \text{ psi}$   $\sigma_2 = \sigma_x = -4302 \text{ psi}$  $\sigma_3 = \sigma_z = -16 490 \text{ psi}$ 

5. Maximum Shear Stress

$$\tau_{\max} = \tau_{1/3} = \frac{\sigma_1 - \sigma_3}{2} = \frac{\sigma_y - \sigma_z}{2} = \frac{-3895 \text{ psi} - (-16 \text{ 490 psi})}{2}$$
$$= 6298 \text{ psi}$$

6. Comparison with results based on Text Figure 4-45:

For 
$$z/b \approx 0.75$$
,

$$\sigma_x \approx -0.3 p_{\text{max}} = -6294 \text{ psi}$$
  

$$\sigma_y \approx -0.2 p_{\text{max}} = -4196 \text{ psi}$$
  

$$\sigma_z \approx -0.8 p_{\text{max}} = -16780 \text{ psi}$$
  

$$\tau_{\text{max}} \approx 0.3 p_{\text{max}} = 6294 \text{ psi}$$

Comparing these results with those calculated using a value of v = 0.211, we find that only  $\sigma_x$  is a function of v;  $\sigma_y$ ,  $\sigma_z$ , and  $\tau_{max}$  are independent of v since the graphical estimates of their values are within 3 % of those obtained from the plot which assumes a Poisson's ratio of 0.3.

7. For a depth of 0.015 in below the cylinder surface,

$$\zeta_b = \frac{0.015 \text{ in}}{1.214 \times 10^{-2} \text{ in}} = 1.236$$

Substituting,

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$$\sigma_{x} = -2v p_{\max} \left[ \sqrt{1 + \zeta_{b}^{2}} - |\zeta_{b}| \right]$$

$$= -2(0.211)(20\,980\,\mathrm{psi}) \left[ \sqrt{1 + (1.236)^{2}} - |1.236| \right]$$

$$= -3133\,\mathrm{psi}$$

$$\sigma_{y} = -p_{\max} \left[ \left( \frac{1 + 2\zeta_{b}^{2}}{\sqrt{1 + \zeta_{b}^{2}}} \right) - 2|\zeta_{b}| \right]$$

$$= (-20\,980\,\mathrm{psi}) \left\{ \left[ \frac{1 + 2(1.236)^{2}}{\sqrt{1 + (1.236)^{2}}} \right] - 2|1.236| \right\}$$

$$= -1652\,\mathrm{psi}$$

$$\sigma_{z} = -p_{\max} \frac{1}{\sqrt{1 + \zeta_{b}^{2}}} = \frac{-20\,980\,\mathrm{psi}}{\sqrt{1 + (1.236)^{2}}}$$

$$= -13\,200\,\mathrm{psi}$$

$$\tau_{\max} = \frac{\sigma_{1} - \sigma_{3}}{2} = \frac{\sigma_{y} - \sigma_{z}}{2} = \frac{-1652 - (-13\,200)}{2} = 5774\,\mathrm{psi}$$

As expected, at a depth corresponding greater than the critical section (z/b = 1.236 > 0.786), the magnitudes of all three principal stresses are smaller than those calculated for z/b = 0.786. The difference between the principal stresses is also smaller and consequently,  $\tau_{max}$  also decreases.