

Appendix A3. Partial Differential Equations

The wave equation

We show how Maple can be used to plot approximations to the solution of the wave equation on a finite domain. See Simmons/Krantz, Chapter 6, Section 2.

Consider string of length L along the x -axis with ends clamped at $x = 0$ and $x = L$. Let $y(x, t)$ denote the vertical displacement at time t of the point in string that is directly above (or below) the point $(x, 0)$. For small vibrations the function y satisfies the wave equation

$$y_{t,t} = a^2 y_{x,x}.$$

The letter a denotes a positive constant determined by the characteristics of the string. Separation of variables leads to solutions of the following form

$$Y_N(x, t) = \sum_{j=1}^N \left(a_j \cos\left(\frac{a j \pi t}{L}\right) + b_j \sin\left(\frac{a j \pi t}{L}\right) \right) \sin\left(\frac{j \pi x}{L}\right), \quad N \text{ a positive integer.}$$

Set the string into motion

The string is set into motion at $t = 0$ by giving it an initial shape $f(x)$ and an initial velocity distribution, $g(x)$. Thus the coefficients a_j and b_j should be chosen so that the function

$$Y_N(x, 0) = \sum_{j=1}^N a_j \sin\left(\frac{j \pi x}{L}\right)$$

approximates $f(x)$ on $[0, L]$ and the function

$$\left. \left(\frac{\partial}{\partial t} Y_N(x, t) \right) \right|_{t=0} = \sum_{j=1}^N \frac{a j \pi b_j}{L} \sin\left(\frac{j \pi x}{L}\right)$$

approximates $g(x)$. Consequently, a_j is the Fourier sine series coefficient for $f(x)$ and $\frac{a j \pi b_j}{L}$ is the Fourier sine series coefficient for $g(x)$.

The following entries define the functions f and g , calculate a_j and b_j , then create various solution curves. We assume that $L = 1$, $a = 1$ and the string is initially stretched "tent like" over the x -axis with shape

$$f(x) = \text{piecewise}(x < 0.5, 0.2 x, 0.2 (1 - x))$$

It is set into motion with a flick of the finger at a point one quarter of the way from the left endpoint

$$g(t) = 0.1 \delta(t - 0.25)$$

You may, of course, change these to fit any situation that you would like to explore.

```
> L := 1: a := 1:
f := x -> piecewise(x < L/2, 2/5*x, 2/5*(L-x)):
g := x -> 1/10*Dirac(x - L/4):
aj := 2/L*int(f(x)*sin(j*Pi*x/L), x=0..L):
bj := L/(a*j*Pi)*2/L*int(g(x)*sin(j*Pi*x/L), x=0..L):
```

The following entry simplifies the formulas for a_j and b_j , then displays them.

```
> c := [aj,bj] assuming j::integer: 'aj'=c[1], 'bj'=c[2];
```

$$a_j = -\frac{2}{5} \frac{-2 \sin\left(\frac{1}{2}j\pi\right) + \cos\left(\frac{1}{2}j\pi\right)j\pi}{j^2\pi^2} + \frac{2}{5} \frac{2 \sin\left(\frac{1}{2}j\pi\right) + \cos\left(\frac{1}{2}j\pi\right)j\pi}{j^2\pi^2}, \quad (1)$$

$$b_j = \frac{1}{5} \frac{\sin\left(\frac{1}{4}j\pi\right)}{j\pi}$$

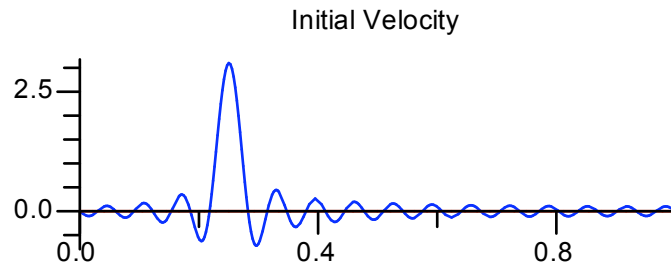
This is the definition of Y as a function of N , x , and t .

```
> Y := (N,x,t) ->
  sum((aj*cos(a*j*Pi*t/L)+bj*sin(a*j*Pi*t/L))*sin(j*Pi*x/L),
      j=1..N);
```

$$Y := (N, x, t) \rightarrow \sum_{j=1}^N \left(a_j \cos\left(\frac{a j \pi t}{L}\right) + b_j \sin\left(\frac{a j \pi t}{L}\right) \right) \sin\left(\frac{j \pi x}{L}\right) \quad (2)$$

The first plot checks that the coefficients are correct for the velocity function g . A check for the shape function f is made when we plot Y at $t=0$ below.

```
> plots[setoptions]( tickmarks = [5,5] );
> plot( [g(x), sum(a*j*Pi*bj/L*sin(j*Pi*x/L), j=1..30)], x=0..L,
        color=[red,blue], title="Initial Velocity");
```

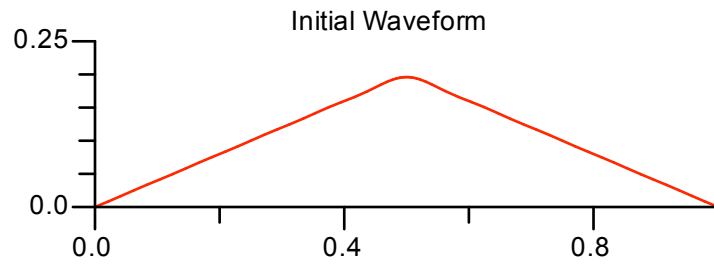


This approximation curve is a typical approximation to a Dirac delta. The area under the curve is approximately $1/10$.

```
> evalf[4]( Int( sum(a*j*Pi*bj/L*sin(j*Pi*x/L), j=1..30), x=0..1));
0.1001 \quad (3)
```

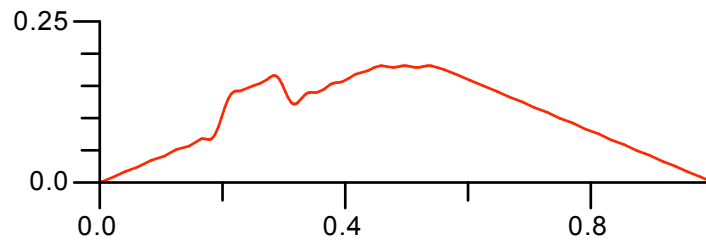
The plot of $Y(20,x,0)$ shows that the a_j coefficients are also correct.

```
> plot( Y(20,x,0), x=0..L, 0..0.25, title="Initial Waveform");
```



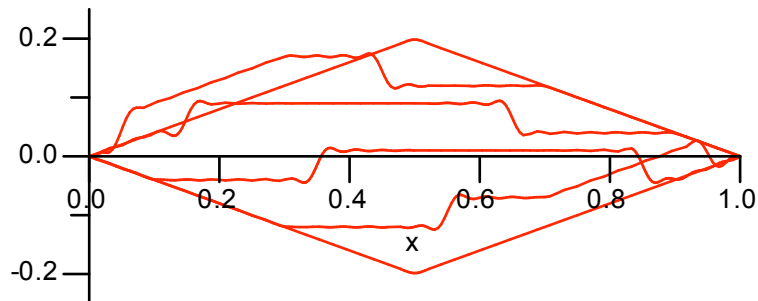
Here is a snapshot of the waveform at $t = 0.05$:

```
> plot( Y(50,x,0.05), x=0..L, 0..0.25 );
```



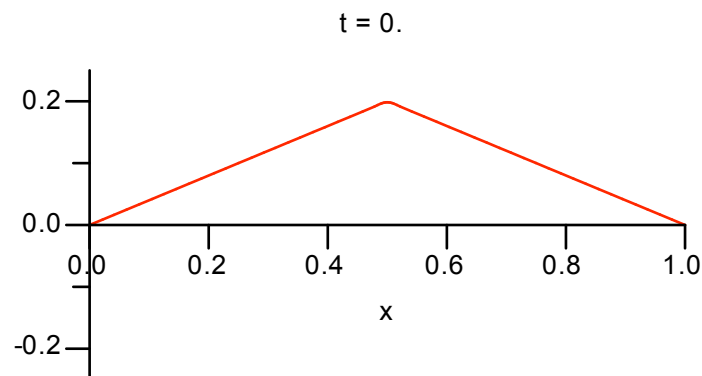
Five snapshots, one every 0.2 seconds:

```
> plot( [Y(50,x,0.2*t)]$t=0..5, x=0..L, -0.25..0.25 );
```



A movie (see the Help page for plots[animate]):

```
> plots[animate]( plot, [ Y(50,x,t), x=0..L, -0.25..0.25],
t=0..2, frames=40);
```



The waveform surface

```
> plot3d( Y(50,x,t), x=0..L, t=0..2, axes=boxed, orientation=[-50,70],  
lightmodel=light2 );
```

