## Assignment 25: Vector-Valued Functions, Part 1 (11.1-3) Name Please provide a handwritten response.

1a. The vector function  $\vec{r}(t) = \langle cos(3t), sin(2t) \rangle$ ,  $0 \le t \le 2\pi$  can be defined by entering the command **Define**  $\vec{r}(t) = [xt1(t), yt1(t)]$  in the entry line of the home screen. You can graph this function by setting the **MODE** to **PARAMETRIC** and letting  $\begin{cases} xt1 = cos(3t) \\ yt1 = sin(2t) \end{cases}$ . Sketch the

resulting curve, known as a "Lissajous curve" on the axes provided below

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$-1 \le x \le 1, -1 \le y \le 1$	

**1b.** You can easily evaluate the points  $\vec{r}(0), \vec{r}\left(\frac{\pi}{4}\right), ..., \vec{r}\left(\frac{n\pi}{4}\right) \quad 0 \le n \le 8$  from the graphing screen on your calculator by pressing F5 Math, 1 Value and entering the  $\theta$  value. Mark these coordinates on the graph above and draw arrows to show the orientation of the curve.

1c. The velocity vector  $\vec{v}(t) = \vec{r}'(t)$  can be defined as **Define**  $\vec{v}(t) = d(\vec{r}(t), t)$ . It can then be evaluated by entering  $\vec{v}(t)$ . Speed is given by  $\|\vec{v}(t)\| = \sqrt{\vec{v}(t) \cdot \vec{v}(t)} = norm(\vec{v}(t))$ . (norm( is found from 2nd 5 MATH, 4 Matrix and selecting the Norm option. Find the speed and record the result below. Sketch the graph of  $\|\vec{v}(t)\| = \begin{cases} xt \ 2 = t \\ yt \ 2 = norm(\vec{v}(t)) \end{cases}$ over

 $0 \le t \le 2\pi$  on the axes below. Based on this graph, does the moving point ever stop?



1d. Define the reparameterization of  $\vec{r}_1(t) = \vec{r}(t+3\sin t)$ ,  $0 \le t \le 2\pi$  and graph the  $\vec{r}_1(t)$ over  $0 \le t \le 2\pi$ . Define  $\begin{cases} xt3(t) = xt1(t+3sint) \\ yt3(t) = yt1(t+3sint) \end{cases}$  as you defined  $\vec{r}(t)$  in 1a and graph

them. What is the subtle difference between this graph and that in part  $\mathbf{a}$ ? Record the graphs on the axes provided.

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$-1 \le x \le 1, -1 \le y \le 1$		
$0 \le t \le 2\pi$		

1e. The velocity vector  $\vec{v}(t) = \vec{r'}_1(t)$  is used to find the speed of a point moving under  $\vec{r}_1(t)$ . Plot the speed of  $\vec{r}_1(t) = \langle xt1(t+3sint), yt1(t+3sint) \rangle$  by imitating part c. Note the approximate values of t where the speed is zero. Use the Solve command on your calculator to find more accurate values of  $\vec{r}(t) = 0$ . What are the coordinates of the points where  $\vec{r}_1(t)$  "stops"? Record your results below.

**2a.** Sketch the graph of  $\vec{r}(t) = \langle 2\cos t + \sin 2t, 2\sin t + \cos 2t \rangle$ ,  $0 \le t \le 2\pi$  on the axes provided below.



**2b**. Find and mark on the graph any stationary points of  $\vec{r}(t)$ , as above.

2c. Define the reparameterization of  $\vec{r}_1(t) = \vec{r}(t + \sin t)$ ,  $0 \le t \le 2\pi$  and graph  $\vec{r}_1(t)$  over  $0 \le t \le 2\pi$ . Check for stationary points. How do the results compare with part b?

**2d.** Repeat part **c** with  $\vec{r}_1(t) = \vec{r}(t^2)$ ,  $0 \le t \le \sqrt{2\pi}$ .